

# Minh-Quan Viet Bui

PH.D. CANDIDATE · COMPUTER VISION · NEURAL RENDERING · 3D/4D RECONSTRUCTION

VIC Lab, KAIST, Daejeon, Republic of Korea

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*“Building Efficient and Generalizable Methods for 3D/4D Scene Understanding”*

## Research Statement

I am a Ph.D. candidate at KAIST (VIC Lab, advised by Prof. Munchurl Kim) specializing in 3D computer vision, neural rendering, and 3D/4D scene reconstruction. My research builds **efficient, robust, and generalizable** representations of 3D/4D scenes from images and videos, spanning from per-scene optimization to feed-forward, generalizable approaches with applications in AR/VR, autonomous systems, computational photography, world modeling, and robotics.

My work has been published at **CVPR 2025 & 2026 (Highlight)**, **ECCV 2026**, **AAAI 2026**, and **IEEE TPAMI** (IF: 20.8). I am actively seeking **visiting researcher, research internship, or postdoctoral positions** in 3D computer vision and world modeling.

## Education

### Korea Advanced Institute of Science and Technology (KAIST)

*Daejeon, Republic of Korea*

PH.D. CANDIDATE, ELECTRICAL ENGINEERING

*Mar. 2022 – Present*

- Advisor: Prof. Munchurl Kim, Visual Intelligence and Computing (VIC) Lab.
- Research areas: 3D Gaussian Splatting (3DGS), Neural Radiance Fields (NeRF), Dynamic Scene Reconstruction, Motion Deblurring, Feed-forward View Synthesis.
- Dissertation topic: *Efficient and Robust 3D/4D Scene Reconstruction from Monocular and Multi-view Images*.
- KAIST Graduate Program Scholarship (full tuition waiver, monthly living stipend).

### Ho Chi Minh City University of Technology – VNU (HCMUT-VNU)

*Ho Chi Minh City, Vietnam*

B.Sc., COMPUTER SCIENCE

*Sep. 2017 – Aug. 2021*

- Thesis: “Monocular 3D Object Detection for Autonomous Driving using Ground-Guide Model and Adaptive Convolution.”

## Research Experience

### Ph.D. Researcher

*Daejeon, Republic of Korea*

VIC LAB, KAIST (ADVISOR: PROF. MUNCHURL KIM)

*Mar. 2022 – Present*

- **AirSplat (ECCV 2026)**: a robust feed-forward 3D Gaussian Splatting framework that adapts 3D vision foundation models for pose-free novel view synthesis; resolves pose-geometry misalignment with a self-consistent pose-alignment feedback loop and rating-based opacity matching that filters degraded primitives.
- **EcoSplat (CVPR 2026 Highlight)**: a feed-forward 3D Gaussian Splatting framework where users specify any target Gaussian count at inference, with no per-scene retraining; best quality across efficiency budgets on RE10K and ACID.
- **MoBGS (AAAI 2026)**: a motion-deblurring dynamic 3D Gaussian Splatting method for blurry monocular video using neural-ODE camera trajectory estimation and physical exposure modeling; **~12% better reconstruction** than prior SOTA on Stereo Blur at **480 FPS**.
- **SplineGS (CVPR 2025)**: a spline-based dynamic 3D Gaussian Splatting framework for real-time rendering from monocular video, eliminating COLMAP preprocessing; **400 FPS** on the NVIDIA dataset.
- **MoBluRF (IEEE TPAMI 2025, IF: 20.8)**: a two-stage motion-deblurring NeRF for blurry monocular video, jointly correcting camera poses and decomposing camera/object motion blur; state-of-the-art on the self-introduced Blurry iPhone benchmark and Stereo Blur.
- **ProNeRF (IEEE Access 2024, IF: 3.4)**: a projection-aware ray sampling network for NeRF that focuses queries on high-density 3D regions; **15–23× faster** than vanilla NeRF with **+0.95 dB** over HyperReel.

### Research Assistant

*Ho Chi Minh City, Vietnam*

HO CHI MINH CITY UNIVERSITY OF TECHNOLOGY (HCMUT-VNU)

*2019 – 2021*

- **Cross-Domain Depth Estimation (Image & Vision Computing 2024, IF: 4.2)**: a meta-learning online domain adaptation framework for monocular depth estimation; state-of-the-art on KITTI Eigen without target-domain supervision.
- **GAC3D / eGAC3D (PeerJ Computer Science 2021 & 2022, IF: 3.8)**: monocular 3D object detection networks using ground-guide geometric priors and depth-adaptive convolutions for accurate 3D bounding-box estimation from single images.

# Publications

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\*Equal contribution / co-first authorship. **9 first/co-first-author publications** (4 top-tier conferences, 5 journals).

## CONFERENCE PAPERS

- [C1] **Minh-Quan Viet Bui\***, Jaeho Moon\*, and Munchurl Kim. "AirSplat: Alignment and Rating for Robust Feed-Forward 3D Gaussian Splatting." *Eur. Conf. Comput. Vis. (ECCV)*, 2026.
- [C2] **Minh-Quan Viet Bui\***, Jongmin Park\*, Juan Luis Gonzalez Bello, Jaeho Moon, Jihyong Oh, and Munchurl Kim. "EcoSplat: Efficiency-controllable Feed-forward 3D Gaussian Splatting from Multi-view Images." *IEEE/CVF Conf. Comput. Vis. Pattern Recognit. (CVPR)*, Denver, CO, 2026. **(Highlight)**
- [C3] **Minh-Quan Viet Bui\***, Jongmin Park\*, Juan Luis Gonzalez Bello, Jaeho Moon, Jihyong Oh, and Munchurl Kim. "MoBGS: Motion Deblurring Dynamic 3D Gaussian Splatting for Blurry Monocular Video." *AAAI Conf. Artif. Intell. (AAAI)*, 2026.
- [C4] Jongmin Park\*, **Minh-Quan Viet Bui\***, Juan Luis Gonzalez Bello, Jaeho Moon, Jihyong Oh, and Munchurl Kim. "SplineGS: Robust Motion-Adaptive Spline for Real-Time Dynamic 3D Gaussians from Monocular Video." *IEEE/CVF Conf. Comput. Vis. Pattern Recognit. (CVPR)*, Nashville, TN, 2025.

## JOURNAL PAPERS

- [J1] **Minh-Quan Viet Bui\***, Jongmin Park\*, Jihyong Oh, and Munchurl Kim. "MoBluRF: Motion Deblurring Neural Radiance Fields for Blurry Monocular Video." *IEEE Trans. Pattern Anal. Mach. Intell. (TPAMI)*, pp. 1–18, 2025, doi: 10.1109/TPAMI.2025.3574644. **[IF: 20.8]**
- [J2] Juan Luis Gonzalez Bello\*, **Minh-Quan Viet Bui\***, and Munchurl Kim. "ProNeRF: Learning Efficient Projection-Aware Ray Sampling for Fine-Grained Implicit Neural Radiance Fields." *IEEE Access*, vol. 12, pp. 56799–56814, 2024, doi: 10.1109/ACCESS.2024.3390753. **[IF: 3.4]**
- [J3] Phan Thi Huyen Thanh\*, **Minh-Quan Viet Bui\***, Duc Dung Nguyen, Tran Vu Pham, Truong Vinh Truong Duy, and Natori Naotake. "Transfer Multi-Source Knowledge via Scale-Aware Online Domain Adaptation in Depth Estimation for Autonomous Driving." *Image Vis. Comput.*, vol. 141, p. 104871, 2024, doi: 10.1016/j.imavis.2023.104871. **[IF: 4.2]**
- [J4] Duc Tuan Ngo\*, **Minh-Quan Viet Bui\***, Duc Dung Nguyen, and Hoang-Anh Pham. "eGAC3D: Enhancing Depth-Adaptive Convolution and Depth Estimation for Monocular 3D Object Pose Detection." *PeerJ Comput. Sci.*, vol. 8, p. e1144, 2022, doi: 10.7717/peerj-cs.1144. **[IF: 3.8]**
- [J5] **Minh-Quan Viet Bui\***, Duc Tuan Ngo\*, Hoang-Anh Pham, and Duc Dung Nguyen. "GAC3D: Improving Monocular 3D Object Detection with Ground-Guide Model and Adaptive Convolution." *PeerJ Comput. Sci.*, vol. 7, p. e686, 2021, doi: 10.7717/peerj-cs.686. **[IF: 3.8]**

# Invited Talks

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**"EcoSplat: Efficiency-controllable Feed-forward 3D Gaussian Splatting from Multi-view Images"**

*IEEE/CVF CVPR 2026, Denver, CO*

NVIDIA BOOTH SPOTLIGHT TALK

June 2026

# Technical Skills

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**Deep Learning** PyTorch, JAX, CUDA, Python  
**Neural Rendering** 3D Gaussian Splatting (3DGS), Neural Radiance Fields (NeRF), Differentiable Rendering, Point Cloud Processing  
**Computer Vision** Dynamic Scene Reconstruction, Novel View Synthesis, Depth Estimation, 3D Object Detection  
**Tools & Platforms** Git, Docker, Linux (Ubuntu), MATLAB, LaTeX

# Honors & Awards

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2026 **Highlight Paper**, EcoSplat, IEEE/CVF Conf. Comput. Vis. Pattern Recognit. (CVPR)

2026 **Outstanding Reviewer**, IEEE/CVF Conf. Comput. Vis. Pattern Recognit. (CVPR)

2022– **KAIST Graduate Program Scholarship**, Full tuition waiver and monthly living stipend

*KAIST*